



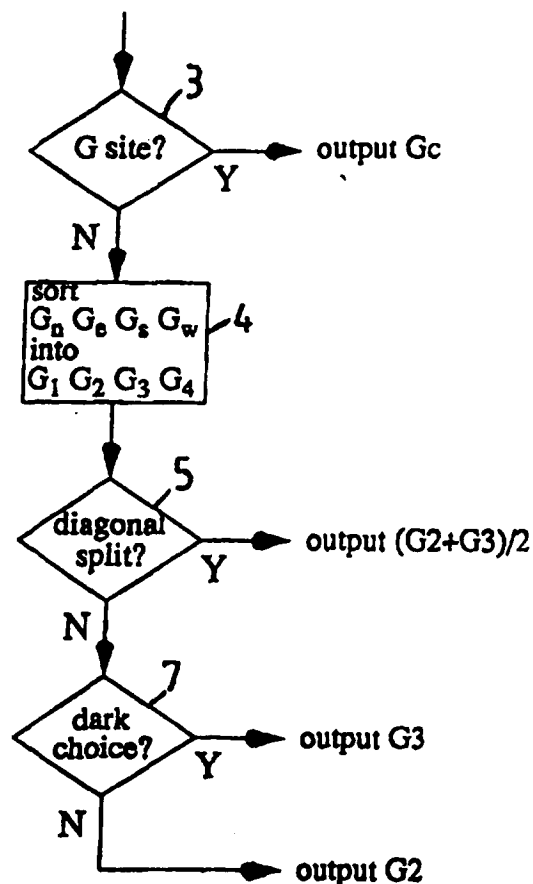
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(54) Title: IMAGE RESTORATION OF A SINGLE-CHIP IMAGE SENSOR

(57) Abstract

The invention relates to a signal processing method for estimating luminance, for use with matrix patterned image sensors where elected sensor pixels (G), preferably green pixels, from which luminance-representative signals are taken, only occupy alternate horizontal and vertical positions in the matrix pattern. The method is designed for detecting luminance contour edges and/or stripes in an image so as to enable images obtained from the sensor to be enhanced. According to the method, each pixel site (Hc) which is at the centre of both a row and a column of five pixels and which is not the site of an elected (green) pixel is identified and for each such identified site (Hc) the signals output from the immediately adjacent four pixels (Gn, Ge, Gs, Gw) in said row and column are processed to establish both signal amplitude and pixel position. A luminance value for the pixel at the identified site (Hc) is evaluated from the amplitude values (G2, G3) of the median pair of said signal amplitudes in accordance with an algorithm where decision taking is based upon the location of the pixels from which the two signals (G1, G2) of highest amplitude emanate. The algorithm is such that when the two signals (G1, G2) of highest amplitude emanate from pixels in the same row or column a further signal processing step is undertaken to identify, in said row and column, the signal outputs from the two respective next adjacent pixels (H1, H4) to the pixels having the highest and lowest signal amplitudes (G1, G4), and the signal output from the pixel at the identified site (Hc), to enable an amplitude comparison to be made according to the result of which one of the said median pair (G2, G3) is selected. Signal processing methods for use with colour, monochrome and mixed colour/monochrome image sensors are claimed, as well as a single-chip camera, and also a video camera system, in which the claimed signal processing methods are implemented.



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IMAGE RESTORATION OF A SINGLE-CHIP IMAGE SENSOR

The present invention relates to image restoration techniques for use with image sensors and in particular to
5 signal processing methods for luminance estimation for use with matrix array image sensors of the type commonly incorporated in video cameras.

The development of low-cost video cameras is driven by the
10 existing Closed Circuit Television (CCTV) camera marketplace and by expected new markets, such as, for example, video conferencing. A major cost of these cameras is the image sensor chip whose cost is a monotonic function of sensor area. Two major goals of sensor designers are to
15 improve sensitivity by increasing pixel area and improve resolution by increasing pixel count. Both of these steps have the disadvantage of increasing sensor area and hence sensor cost. If the sensor area is to remain constant then, until now, image resolution could only be increased
20 at the cost of lowered sensitivity of the sensor and sensitivity could only be increased at the cost of lowered resolution.

In one known type of video camera a colour image is formed
25 on a single image sensor device which is spatially divided into many (typically 100,000 or more) pixels and each pixel is covered with a colour filter corresponding to one of a number of desired spectral components. These may typically be red, green and blue components or, for example, cyan,
30 magenta and yellow. Further colour sets are also sometimes used.

Many different types of colour matrix patterns are possible. The signal outputs of all the pixels are
35 combined by means of a reading operation at the sensor device output. Many image restoration techniques have been developed for combining the signals from individual pixels in the matrix array into a composite image representation

which presents a "real"-looking image to the human eye. One known technique involves superimposing a highpass-filtered or "edge-extracted" luminance signal onto lowpass-filtered or "spatially smoothed" component colour signals (e.g. red, green, blue) obtained from the pixel matrix. Such image restoration techniques can enhance the perceived resolution or "sharpness" of the video camera image.

One problem associated with image restoration is obtaining an accurate luminance signal from the sensor. It is known that the green spectral component is closely related to the luminance response of the human eye. It has therefore been known to use the signal outputs of green pixels, or alternatively another colour of pixel whose colour is representative of luminance, to obtain the necessary luminance signal. As the chosen colour of pixels (e.g. green) only account for some of the pixels in a colour image sensor array, however, it is desirable to estimate luminance at the remaining pixel sites.

It is an object of the present invention to provide a signal processing method for accurately estimating luminance for use in matrix array colour image sensors.

US 4 630 307 describes a signal processing method for estimating luminance for use in matrix array sensors having luminance-sensing pixels arranged in a chequerboard pattern. The method uses signals obtained from luminance-sensing pixels to estimate luminance values at pixels in the matrix array which are not capable of sensing luminance.

In the following text the term "row" is defined as a horizontal row and the term "column" is defined as a vertical row.

According to a first aspect, the present invention comprises a signal processing method for estimating luminance, for use with matrix patterned image sensors where elected sensor pixels from which luminance-
5 representative signals are taken only occupy alternate horizontal and vertical positions in the matrix pattern, the method comprising
identifying each pixel site which is at the centre of both
a row and a column of five pixels and which is not the site
10 of a said elected sensor pixel, and for each such identified site processing the signals output from the immediately adjacent four pixels in said row and column to establish both signal amplitude and pixel position and evaluating a luminance value for the pixel of the
15 identified site from the amplitude values of the median pair of said signal amplitudes in accordance with an algorithm where decision taking is based upon the location of the pixels from which the two signals of highest amplitude emanate, the algorithm being such that when the
20 two signals of highest amplitude emanate from pixels in the same row or column a further signal processing step is undertaken to identify, in said row and column, the signal outputs from the two respective next adjacent pixels to the pixels having the highest and lowest signal amplitudes, and
25 the signal output from the pixel at the identified site, to enable an amplitude comparison to be made according to the result of which one of the said median pair is selected.

One advantage of the signal processing method according to
30 the first aspect of the invention is that it utilizes signal outputs from pixels in said row and column which pixels are next adjacent to the highest and lowest amplitude ones of said four pixels immediately adjacent the identified site.

35

Preferably, the selected one of said median pair is the higher amplitude one where the signal output from the next adjacent pixel to said pixel having the highest signal

amplitude is closer in amplitude to the signal output from the pixel at the identified site than the signal output from the next adjacent pixel to said pixel having the lowest signal amplitude. Preferably, also, the selected
5 one is the lower amplitude one of said median pair where the signal output from the next adjacent pixel to said pixel having the lowest signal amplitude is closer in amplitude to the signal output from the pixel at the identified site than the signal output from the next
10 adjacent pixel to said pixel having the highest signal amplitude.

According to a second aspect the present invention comprises a signal processing method for estimating
15 luminance for use with matrix array colour image sensors in which elected luminance-sensing pixels capable of producing signals representative of luminance are arranged in a chequerboard pattern with colour sensing pixels which are capable of producing signals representative of colour, the
20 method comprising the steps of: ranking the signal values representative of luminance obtained from a cluster of four luminance-sensing pixels surrounding a first colour-sensing pixel, analyzing the spatial distribution of said ranked signal values so as to detect the presence of any diagonal
25 luminance contour edge, horizontal luminance contour stripe or vertical luminance contour stripe at said first colour-sensing pixel, and determining an estimated discrete signal value representative of luminance for said first colour-sensing pixel based on one or more middle ranked signal
30 values in a colour-enhancing fashion dependent upon, firstly, whether any diagonal luminance contour edge is detected and, secondly, whether any horizontal or vertical luminance contour stripe which is detected is interpreted as a dark stripe on a light background or a light stripe on
35 a dark background, wherein when a horizontal or vertical luminance contour stripe is detected, the signal values representative of colour obtained from a plurality of said colour-sensing pixels in the vicinity of said cluster of

four luminance-sensing pixels are compared so as to determine whether said detected horizontal or vertical luminance contour stripe is interpreted as a dark stripe on a light background or a light stripe on a dark background.

5

One advantage of the signal processing method according to the second aspect of the invention is that it utilizes colour signal values from pixels other than said elected luminance-sensing pixels to influence the estimated
10 luminance signal value for said first colour-sensing pixel.

Preferably, said plurality of colour-sensing pixels in the vicinity of said cluster of four luminance-sensing pixels includes said first colour-sensing pixel, a second colour-
15 sensing pixel disposed within the detected luminance contour stripe and a third colour-sensing pixel disposed outwith the detected luminance contour stripe. This increases the likelihood of accurately detecting and enhancing horizontal and vertical luminance contour stripes
20 occurring in the image. The method thus enables real-time images obtained from the image sensor to be enhanced so as to improve the perceived resolution of the sensor to the human eye.

25 The estimated discrete signal value representative of luminance is preferably based on the mean of the middle ranking signal values when a diagonal contour edge is detected at first colour-sensing pixel.

30 Advantageously, said estimated discrete value is based on a corresponding one of the two middle ranking values when a stripe detected at said first colour-sensing pixel is interpreted as a dark stripe on a light background or as a light stripe on a dark background. Preferably said
35 corresponding one of the two middle ranking signal values is the lower ranked one when a dark stripe on a light background is detected and is the higher ranked one when a light stripe on a dark background is detected.

A diagonal contour edge is preferably detected when the two highest ranking signal values are obtained from luminance-sensing pixels disposed diagonally adjacent one another.

5

A horizontal or vertical contour stripe is preferably detected when the two highest ranking signal values are obtained from luminance-sensing pixels disposed horizontally or vertically opposite one another.

10

Where a horizontal or vertical stripe is detected, the signal value obtained from said first colour-sensing pixel is preferably compared with the signal values obtained from second and third colour-sensing pixels disposed respectively vertically and horizontally opposite said first colour-sensing pixel and immediately adjacent to the luminance-sensing pixels having the highest and lowest ranked signal values. Conveniently, if the signal value of said first colour-sensing pixel is closest in value to the signal value of the pixel immediately adjacent said highest ranked signal value pixel the stripe is interpreted as a light stripe on a dark background and if the signal value of the first colour-sensing pixel is closest in value to the signal value pixel of the pixel immediately adjacent said lowest ranked signal value pixel the stripe is interpreted as a dark stripe on a light background.

25

Said elected luminance-sensing pixels may be pixels which are capable of producing signals representative of both luminance and colour.

30

The signal processing steps of the method according to the second aspect of the invention are preferably repeated for every colour-sensing pixel in the matrix array sensor which is not also an elected luminance-sensing pixel and which is at the centre of both a row and a column of five pixels. In this manner a respective estimated discrete signal value

35

representative of luminance is determined for each such colour-sensing pixel in the matrix array.

The estimated luminance signal value obtained from each
5 such colour-sensing pixel in the array may provide a
luminance signal for a luminance channel of a camera
incorporating the image sensor array. Said estimated
luminance channel signal may be highpass-filtered to obtain
an "edge-extracted" luminance signal. Alternatively, said
10 estimated luminance signal may be lowpass-filtered and
further processed to produce a signal which approximates to
an "edge-extracted" luminance signal.

Signals representative of colour obtained from colour-
15 sensing pixels in the array may be processed to obtain
lowpass-filtered colour channel signals in a colour camera
which incorporates the sensor array. Where said elected
luminance-sensing pixels also sense colour, the signals
from the elected luminance-sensing pixels in the array may
20 also be processed to obtain a lowpass-filtered signal for
an additional colour channel. The "edge-extracted"
luminance signal may be superimposed on said colour channel
signals to obtain full colour and luminance information for
every pixel which is used to produce a contour-enhanced
25 (i.e. improved resolution) image to the human-eye.

The elected luminance-sensing pixels are preferably green
pixels. The colour-sensing pixels are preferably red and
blue pixels. Alternatively, the matrix array is comprised
30 of magenta, cyan and yellow pixels. Other colour sets are
also possible.

Where the matrix array is comprised of red, green and blue
pixels, the pixel signals are read into respective red,
35 green and blue colour channels. The three colour channel
signals are preferably processed to obtain lowpass-
filtered, "spatially-smoothed" respective red, green and

blue channel signals. In this way, red, green and blue colour information is obtained for every pixel in the array.

- 5 Where green pixels are the elected luminance-sensing pixels, the green signal values are preferably used in raw, uncorrected colour form.

10 The matrix array image sensor may, alternatively, comprise a mixed colour and monochrome array in which monochrome, luminance-sensing pixels are arranged in a chequerboard pattern with colour-sensing pixels.

- 15 According to a third aspect, the invention comprises a signal processing method for estimating luminance, for use with matrix patterned sensors where elected sensor pixels from which luminance-representative signals are taken only occupy alternate horizontal and vertical matrix element positions in the matrix pattern,
- 20 the method comprising identifying each matrix element site which is at the centre of both a row and a column of seven matrix elements and which is not the site of a said elected sensor pixel, and for each such identified site processing the signals output
- 25 from the immediately adjacent four pixels in said row and column to establish both signal amplitude and pixel position and evaluating a luminance value for the matrix element of the identified site from the amplitude values of the median pair of said signal amplitudes in accordance
- 30 with an algorithm where decision taking is based upon the location of the pixels from which the two signals of highest amplitude emanate, the algorithm being such that when the two signals of highest amplitude emanate from pixels in the same row or column a further signal
- 35 processing step is undertaken to identify outputs in said row and column from the two pixels respectively next adjacent to the pixels having the highest and lowest signal amplitudes, and to identify the mean of the signal outputs

from the eight pixels diagonally adjacent to, and arranged around, said four pixels in said row and column, to enable an amplitude comparison to be made according to the result of which one of the said median pair is selected.

5

According to a fourth aspect the invention comprises a signal processing method for estimating luminance for use in a matrix array monochrome image sensor in which elected luminance-sensing pixels capable of producing signals
10 representative of luminance are arranged in a chequerboard pattern with non-luminance-representative matrix array elements which do not produce signals, the method comprising the steps of: ranking the signal values representative of luminance obtained from a cluster of four
15 luminance-sensing pixels surrounding a first non-luminance-representative matrix element, analyzing the spatial distribution of said ranked signal values so as to detect the presence of any diagonal luminance contour edge, horizontal luminance contour stripe or vertical luminance
20 contour stripe at said first non-luminance-representative matrix element, and determining an estimated discrete signal value representative of luminance for said non-luminance-representative matrix element based on one or more middle ranked signal values in a contour-enhancing
25 fashion dependent upon, firstly, whether any diagonal luminance contour edge is detected and, secondly, whether any horizontal or vertical luminance contour stripe which is detected is interpreted as a dark stripe on a light background or a light stripe on a dark background, wherein,
30 when a horizontal or vertical luminance contour stripe is detected the signal values representative of luminance obtained from at least second and third luminance-sensing pixels disposed respectively within and outwith the detected luminance contour stripe are compared with the
35 mean of the signal values obtained from a plurality of further luminance-sensing pixels in the vicinity of said cluster of four luminance-sensing pixels so as to determine whether said horizontal or vertical stripe is interpreted

as a dark stripe on a light background or a light stripe on a dark background.

An advantage of this fourth method is that the signal value
5 from at least one pixel disposed within the detected
luminance contour stripe is compared with signal values
from pixels disposed outwith said stripe so as to determine
whether the stripe should be interpreted as a dark stripe
on a light background or a light stripe on a dark
10 background.

Preferably said plurality of further luminance-sensing
pixels comprise eight pixels, each pixel being disposed
diagonally adjacent one of said cluster of four luminance-
15 sensing pixels surrounding said first non-luminance
representative matrix element.

Advantageously said second and third luminance-sensing
pixels are disposed horizontally and vertically opposite
20 said first non-luminance representative matrix element and
adjacent to the two of the cluster of four luminance-
sensing pixels which have the highest and lowest ranked
signal values.

25 The steps of the signal processing method according to the
fourth aspect of the invention may be repeated for each
non-luminance representative matrix element in the matrix
array which is at the centre of both a row and a column
containing seven matrix elements.

30 According to a fifth aspect, the invention provides a
camera comprising a matrix array image sensor and signal
processing means for carrying out the signal processing
method according to any of the above-mentioned first,
35 second, third and fourth aspects of the invention. The
image sensor may be a Charge Coupled Device (CCD) or CMOS
array.

Preferred embodiments of the invention will now be described by way of example only and with reference to the accompanying drawings in which:

- 5 Fig. 1 is a schematic illustration of a 5 x 5 portion of a colour (RGB) matrix image sensor which may be used with a signal processing method for luminance estimation according to the invention;
- Fig. 2 is a schematic illustration of a 5 x 5 pixel
10 template centered on a non-Green pixel, Hc, of the image sensor of Fig. 1;
- Figs. 3 (a) and (b) illustrate two possible situations where a horizontal or vertical stripe is detected at the non-Green pixel, Hc, of Fig. 2;
- 15 Fig. 4 is a flow diagram illustrating schematically a luminance estimation method according to the invention;
- Fig. 5 is a schematic illustration of a 4 x 4 portion of a mixed colour and monochrome matrix image sensor;
- Fig. 6 is a schematic illustration of a portion of a
20 monochrome image sensor array which may be used with a further method according to the invention;
- Fig. 7 is a block diagram illustrating schematically a single-chip colour video camera in which signal processing methods according to the invention are carried out; and
- 25 Fig. 8 is a block diagram illustrating schematically a video camera system 40 incorporating the chip camera of Fig. 7.

Fig. 1 illustrates schematically a 5 x 5 pixel portion 1 of
30 a single image sensor device having a Red (R), Green (G), Blue (B) colour matrix pattern as disclosed in US 3 971 065 (Bayer). The pattern contains more Green (G) pixels than Red (R) or Blue (B) because Green is the principal, primary colour component of luminance. The Green pixels are
35 disposed in a chequerboard pattern with the non-green (i.e. R,B) pixels, the green pixels (G) thus occupying alternate horizontal and vertical positions in the matrix.

The sensor device is spatially divided into typically 100,000 or more pixels and each pixel is covered with a colour filter corresponding to the desired spectral components. The device is incorporated in an electric camera (see Figs. 7 and 8) in which signal outputs from the pixels are read out at an array output of the sensor device to provide three component colour channels, as in a normal electronic colour camera.

10 The component colour channels are interpolated to provide missing data by lowpass-filtering using a square area template, typically 5 x 5 pixels. Although Green data is more plentiful than Red or Blue, and accordingly more Green pixels are covered by the lowpass-filter template than Red or Blue, the Green colour-signal is essentially treated identically to Red and Blue. In each case, the component colour channel represents a lowpass-filtered (spatially smoothed) version of the ideal component colour channel response.

20 In addition to the three component colour channels normally present in an electronic colour camera, we form a fourth channel representing an estimate of luminance. This is achieved using the following process.

25 The Green pixels (G) are elected to be "luminance-sensing" pixels and Green pixel signals are taken to be representative of luminance as well as being representative of Green colour. Green is the dominant contributor to luminance, as perceived by the human eye, and is the most densely sampled colour component in the matrix pattern of the Fig. 1 sensor device. It is used in a unique fashion when estimating luminance. The luminance estimate is constructed by interpolating non-Green pixels in a luminance contour-enhancing fashion, complementing the contour-suppressing interpolation of the colour channel processing.

The operations described below are symmetrical in an orthogonal sense, that is to say transformations such as mirroring or rotation through multiples of 90 degrees do not change their result. With no loss of generality, we
5 associate compass direction N (north) with the top of the image.

Sites where Green is present require no processing. In this case luminance is given by the centre-pixel output,
10 Gc. A luminance estimate for each "missing Green" (i.e. Red (R) or Blue (B) site) which is at the centre of both a row and a column of five pixels is obtained using a 5 x 5 template 2 centred on the "missing Green" site, Hc, as illustrated schematically in Fig. 2, wherein neighbours to
15 the N,S,E and W are known to be Green. These appear as Gn, Ge, Gs, and Gw in Fig. 2. We identify non-Green pixels in the 5 x 5 pixel vertical cross pattern of Fig. 2 as Hn, He, Hs, and Hw, being the far-neighbours of Gn, Ge, Gs and Gw respectively. These H pixels will all be either Red or
20 Blue depending on the colour of the centre pixel Hc.

In the first method described here, we first sort the four G neighbours by descending order of value (i.e. amplitude) into G1 (max), G2, G3, G4 (min). If G1 and G2 form a
25 diagonally-adjacent pair then we infer that the image contains a local diagonal edge (of a luminance contour) and the missing luminance value is estimated or "restored" as the average of the median pair, G2 and G3. In this case the values of H pixels are unused.

30 If G2 and G3 are horizontally or vertically opposed across the "missing Green" pixel, Hc, for example as shown in Figs. 3 (a) and (b), we infer that the image contains part of a horizontal or vertical luminance contour line or "stripe".
35 To determine whether the stripe is a dark stripe on a light background or a light stripe on a dark background we examine the far neighbours H1 and H4 of G1 and G4

respectively to determine which of these is closer in value to H_c . If H_1 is closer then we infer that we have a light stripe on a dark background and we restore luminance at the missing Green site, H_c , at a value equal to G_2 , i.e. the higher of the two middle ranked values G_2 , G_3 . If H_4 is closer we infer that we have a dark stripe on a light background and we restore luminance at H_c at a value equal to G_3 i.e. the lower of the two middle ranked values. In each case these median values (G_2 , G_3) are generally safer alternatives to the maximum or minimum values (G_1 , G_4).

Fig. 4 illustrates a decision flow chart which summarizes the luminance estimation method applied so as to step through the image, examining every pixel site which is at the centre of both a row and a column of five pixels. The first branch 3 depends on whether the centre-pixel site contains a Green pixel or not. If yes (Y), the green signal G_c is output. If no (N), G_n , G_c , G_s , and G_w are sorted into G_1 , G_2 , G_3 , G_4 (see box 4). The second branch 5 depends on whether a diagonal split is detected, i.e. G_1 is diagonally adjacent to G_2 . The third branch 7 is dependent on whether a "dark choice" is made, i.e. far-neighbouring H_4 is closer than H_1 in value to H_c .

G_1 and G_2 being horizontally or vertically opposed across the "missing Green" pixel, H_c , may also indicate respectively the presence of a sharp horizontal or vertical luminance contour edge (rather than a stripe) in the image. The second branch of the decision process, i.e. the "dark choice" of Fig. 4, produces equally acceptable restored luminance values for the missing-Green pixel in this scenario. Flat, i.e. relatively constant luminance, areas of the image will also be detected as either diagonal edges, or vertical or horizontal stripes, using the above-described processing method, which produces acceptable restored luminance values for such flat areas.

The estimated luminance signal obtained for a non-Green pixel sited at the centre of both a row and a column of five pixels provides an estimated luminance signal for the fourth i.e. luminance channel of the camera. This signal
5 then has subtracted from it a spatially smoothed version of the luminance-representative signal, this being the particular output of a 5 x 5 square area lowpass-filtering template corresponding to the colour used for luminance sensing (in this case Green). This technique, sometimes
10 known as "un-sharp masking", obtains a signal which approximates to a highpass-filtered (i.e. "edge-extracted") luminance signal. The "edge-extracted" signal is then superimposed on to the spatially-smoothed colour channel signals obtained over the same 5 x 5 pixel area so as to
15 produce a Red, Green, Blue (RGB) pixel triplet including full colour and luminance information. RGB pixel triplet signals obtained in this way enable the camera to produce a contour-enhanced image which is more resolved, and thus more pleasing, to the human eye, than the image obtained
20 purely from the spatially smoothed colour channel signals.

The above-described luminance estimation signal processing method restores luminance values to most pixel sites in the sensor array and gives subjectively excellent "end-image"
25 results for most real scenes.

The method is particularly successful in detecting and restoring luminance contours of diagonal edge, vertical stripe and horizontal stripe forms, these having been
30 particularly difficult to detect and restore accurately using previously known luminance estimation/interpolation techniques.

Conveniently, in its "raw" form Green contains components of
35 Red and Blue present due to imperfections of the Green filter spectral response, which can improve its utility as an estimate of luminance. Although it is normal practice

to compensate electronically for incorrect colour rendering, it is better to apply luminance estimation processing before colour-compensation processing on Green.

- 5 It should be noted that colour combinations other than RGB may be used. The above procedure may produce similarly good results for these alternative combinations provided the colour that is elected for the luminance-sensing pixels in place of Green is representative of luminance to the
10 human eye. For example, a yellow, cyan, magenta colour combination could be used.

The image sensor device is typically a CCD or CMOS array sensor. The production process for both types of sensor is
15 well disposed to deposition of the colour filters when the products are in silicon-wafer form. This enhances cost benefit. Signal processing circuitry for carrying out the above-described luminance estimation according to the flow chart of Fig. 4 can be provided in the image sensor chip,
20 if desired. Alternatively, or additionally, separate electronic circuitry can be provided in the camera.

Fig. 5 shows schematically a portion 8 of a mixed monochrome and colour image sensor in which monochrome
25 (e.g. white, unfiltered) pixels (Y) are arranged in a chequerboard pattern with coloured pixels which may be coloured in accordance with any desired colour set but in Fig. 5 are shown as Red(R), Green(G), Blue(B) pixels. The luminance estimation method described in relation to Figs.
30 1 to 4 can also be applied to this type of sensor array by electing the monochrome pixels as the "luminance-sensing" pixels. Colour restoration is not applied in this case.

The above-described luminance estimation method can also be
35 adapted for application to a monochrome matrix array image sensor. Fig. 6 shows schematically a portion 9 of a monochrome sensor array in which photosensitive pixels (P), shown in white, are arranged in a chequerboard pattern with

non-photosensitive areas (N), shown shaded, which are occupied by overhead (light-insensitive) circuitry.

A cluster of four pixels Y_n , Y_e , Y_s , Y_w surrounding a non-photosensitive centre site C take the place of G_n , G_e , G_s , G_w respectively in Fig. 2. These are ranked in descending value order as Y_1 (max), Y_2 , Y_3 , Y_4 (min) and are used to obtain a median average (the mean of Y_2 and Y_3) for estimated luminance at centre site C in cases where a diagonal split is detected. The principal difference between the monochrome technique for Fig. 6 and the colour technique for Fig. 2 is in the "dark choice" step, required in cases where a diagonal split is not detected. Here, in order to infer whether the image contains a dark stripe on a light background or a light stripe on a dark background, the pixels X_n , X_e , X_s , X_w , which are the far neighbours of Y_n , Y_e , Y_s , Y_w in a vertical cross pattern centered on C, take the place of H_n , H_e , H_s , H_w in Fig. 2 respectively. H_c in Fig. 2 is, however, unobtainable in this case as centre-site C does not contain a pixel. Instead, we calculate the average (i.e. mean) of the eight ring-surrounding pixels, X_c , which are located diagonally adjacent to Y_n , Y_e , Y_s , Y_w as shown in Fig. 6. The far neighbours X_1 and X_4 of Y_1 (max) and Y_4 (min) respectively are compared with the mean, M , of the eight ring-surrounding pixels, X_c . If X_1 is closer in value than X_4 to M we infer a dark stripe on a light background and luminance is estimated or "restored" at centre-site C as Y_3 . If X_4 is closer in value than X_1 to M we infer a light stripe on a dark background and luminance is estimated or restored at C as Y_2 .

By using this "monochrome" luminance estimation method, the pixels representing luminance can be maximized in size (50% of the number of pixels present in the colour array of Fig. 1 having effectively been discarded in the monochrome version of the array) to enable the realization of a monochrome video camera of increased sensitivity without

the resulting unacceptable loss of image resolution, due to the lower pixel count, which would be experienced if the luminance estimation technique were not employed.

5 The skilled reader will be aware of various suitable ways of implementing the necessary electronic circuitry to perform the signal processing operations illustrated by Fig. 4. This may be achieved, for example, in integrated circuitry which may, as afore-mentioned, be provided on the
10 image sensor chip. Fig. 7 is a schematic architectural overview of a single-chip colour video camera 20. The camera 20 incorporates a sensor subsystem 21 comprising a control unit 22, and image sensor array 23, and a readout unit 24. Sensor output S, is digitised (block A/D) in a
15 processor subsystem 25 and stored in a 5-line memory 26. As a new pixel is written into memory, a 5 x 5 pixel block is read out from 5-pixel registers 27 and processed in two channels, the upper channel including a lowpass filter 28 and processor block 29 acting on colour data. The lower
20 channel includes signal processing apparatus at block 30 for carrying out the luminance estimation signal processing method already described. A subtractor circuit 35 is used to perform the un-sharp masking process in which the spatially-smoothed version of the Green signal is
25 subtracted from the luminance estimate signal. After further processing at block 31 to obtain the "edge-extracted" luminance signal, the colour and luminance signals are recombined using adding circuit 32 to produce the final RGB pixel triplet. A timing generator 33 is also
30 provided for the processor subsystem 25 as shown in Fig. 7.

Fig. 8 shows an NTSC or PAL (phase alternate line) video camera system 40 incorporating the chip camera 20 of Fig. 7. The system 40 includes an NTSC or PAL encoder 42 which
35 receives the RGB video signal V and a synchronising signal Z from the camera 20. The system also includes a resonant crystal 44 which functions as a master clock for driving the camera 20.

CLAIMS

1. A signal processing method for estimating luminance, for use with matrix patterned image sensors where elected
5 sensor pixels (G) from which luminance-representative signals are taken only occupy alternate horizontal and vertical positions in the matrix pattern, the method comprising
identifying each pixel (Hc) which is at the centre of both
10 a row and a column of five pixels and which is not the site of a said elected sensor pixel (G), and for each such identified site (Hc) processing the signals output from the immediately adjacent four pixels (Gn, Ge, Gs, Gw) in said row and column to establish both signal amplitude and pixel
15 position and evaluating a luminance value for the pixel of the identified site from the amplitude values (G2, G3) of the median pair of said signal amplitudes in accordance with an algorithm where decision taking is based upon the location of the pixels from which the two signals (G1, G2)
20 of highest amplitude emanate, the algorithm being such that when the two signals (G1, G2) of highest amplitude emanate from pixels in the same row or column a further signal processing step (7) is undertaken to identify, in said row and column, the signal outputs from the two respective next
25 adjacent pixels (H1, H4) to the pixels having the highest and lowest signal amplitudes (G1, G4), and the signal output from the pixel at the identified site (Hc), to enable an amplitude comparison to be made according to the result of which one of the said median pair (G2, G3) is
30 selected.

2. A signal processing method according to claim 1, wherein the selected one of said median pair (G2, G3) is the higher amplitude one (G2) where the signal output from the next
35 adjacent pixel (H1) to said pixel having the highest signal amplitude (G1) is closer in amplitude to the signal output from the pixel at the identified site (Hc) than the signal

output from the next adjacent pixel(H4) to said pixel having the lowest signal amplitude (G4).

3. A signal processing method according to claim 1 or claim
5 2, wherein the selected one of said median pair (G2, G3) is the lower amplitude one (G3) where the signal output from the next adjacent pixel (H4) to said pixel having the lowest signal amplitude (G4) is closer in amplitude to the signal output from the pixel at the identified site (Hc)
10 than the signal output from the next adjacent pixel (H1) to said pixel having the highest amplitude (G1).

4. A signal processing method for estimating luminance for use with matrix array colour image sensors in which elected
15 luminance-sensing pixels (G) capable of producing signals representative of luminance are arranged in a chequerboard pattern with colour sensing pixels (R, B) which are capable of producing signals representative of colour, the method comprising the steps of: ranking the signal values (G1, G2,
20 G3, G4) representative of luminance obtained from a cluster of four luminance-sensing pixels (Gn, Ge, Gs, Gw) surrounding a first colour-sensing pixel (Hc), analysing the spatial distribution of said ranked signal values (G1, G2, G3, G4) so as to detect the presence of any diagonal
25 luminance contour edge, horizontal luminance contour stripe or vertical luminance contour stripe at said first colour-sensing pixel (Hc), and determining an estimated discrete signal value representative of luminance for said first colour-sensing pixel based on one or more middle ranked
30 signal values (G2, G3) in a contour-enhancing fashion dependent upon, firstly, whether any diagonal luminance contour edge is detected and, secondly, whether any horizontal or vertical luminance contour stripe which is detected is interpreted as a dark stripe on a light
35 background or a light stripe on a dark background, wherein when a horizontal or vertical luminance contour stripe is detected the signal values representative of colour obtained from a plurality of said colour-sensing pixels (R,

B) in the vicinity of said cluster of four luminance-sensing pixels (Gn, Ge, Gs, Gw) are compared so as to determine whether said detected horizontal or vertical luminance contour stripe is interpreted as a dark stripe on a light background or a light stripe on a dark background.

5. A signal processing method according to claim 4, wherein said plurality of colour-sensing pixels in the vicinity of said cluster of four luminance-sensing pixels (Gn, Ge, Gs, Gw) includes said first colour-sensing pixel (Hc), a second colour-sensing pixel (H1, H4) disposed within the detected luminance contour stripe and a third colour-sensing pixel (H4, H1) disposed outwith the detected luminance contour stripe.

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6. A signal processing method according to claim 4 or claim 5, wherein the estimated discrete signal value representative of luminance is based on the mean of the middle ranking signal values (G2, G3) when a diagonal contour edge is detected at said first colour-sensing pixel (Hc).

7. A signal processing method according to any of claims 4 to 6, wherein said estimated discrete signal value is based on a corresponding one of the two middle ranking values (G2, G3) when a stripe detected at said first colour-sensing pixel (Hc) is interpreted as a dark stripe on a light background or as a light stripe on a dark background.

8. A signal processing method according to claim 7, wherein said corresponding one of the two middle ranking signal values (G2, G3) is the lower ranked one (G3) when a dark stripe on a light background is detected and is the higher ranked one (G2) when a light stripe on a dark background is detected.

9. A signal processing method according to any of claims 4 to 8, wherein a diagonal contour edge is detected when the

two highest ranking signal values (G1, G2) are obtained from luminance-sensing pixels (G) disposed diagonally adjacent one another.

- 5 10. A signal processing method according to any of claims 4 to 9, wherein a horizontal or vertical contour stripe is detected when the two highest ranking signal values (G1, G2) are obtained from luminance-sensing pixels (G) disposed horizontally or vertically opposite one another.

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11. A signal processing method according to any of claims 4 to 10, wherein, where a horizontal or vertical stripe is detected, the signal value obtained from said first colour sensing pixel (Hc) is preferably compared with the signal
15 values obtained from second and third colour-sensing pixels (H1, H4) disposed respectively vertically and horizontally opposite said first colour-sensing pixel (Hc) and immediately adjacent to the luminance-sensing pixels having the highest and lowest ranked signal values (G1, G4), and
20 if the signal value of said first colour-sensing pixel (Hc) is closest in value to the signal value of the pixel (H1) immediately adjacent to said highest-ranked signal value (G1) the stripe is interpreted as a light stripe on a dark background, and if the signal value of said first colour-
25 sensing (Hc) is closest in value to the signal value of the pixel (H4) immediately adjacent to said lowest-ranked signal value (G4) the stripe is interpreted as a dark stripe on a light background.

- 30 12. A signal processing method according to any of claims 4 to 11, wherein the steps of the method are repeated for every colour-sensing pixel (R,B) in the matrix array sensor which is not also an elected luminance-sensing pixel (G) and which is at the centre of both a row and a column of
35 five pixels.

13. A signal processing method according to any of claims 4 to 12, wherein the estimated discrete signal value

representative of luminance obtained from each said colour sensing pixel (R, B) in the array is used to provide a luminance signal for a luminance channel (35, 31) of a camera (20) incorporating the image sensor array (23),
5 which luminance signal is further processed to obtain an "edge-extracted" luminance signal which is, in turn, superimposed on lowpass filtered colour channel signals (R, G, B) in the camera (20) so as to provide luminance information for every pixel in the array.

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14. A signal processing method for estimating luminance, for use with matrix patterned sensors where elected sensor pixels (P) from which luminance-representative signals are taken only occupy alternate horizontal and vertical matrix
15 element positions in the matrix pattern, the method comprising identifying each matrix element site (C) which is at the centre of both a row and a column of seven matrix elements and which is not the site of a said elected sensor pixel
20 (P), and for each such identified site (C) processing the signals output from the immediately adjacent four pixels (Yn, Ye, Ys, Yw) in said row and column to establish both signal amplitude and pixel position and evaluating a luminance value for the matrix element of the identified
25 site (C) from the amplitude values of the median pair (Y2, Y3) of said signal amplitudes in accordance with an algorithm where decision taking is based upon the location of the pixels from which the two signals (Y1, Y2) of highest amplitude emanate, the algorithm being such that
30 when the two signals (Y1, Y2) of highest amplitude emanate from pixels in the same row or column a further signal processing step is undertaken to identify outputs (X1, X4) in said row and column from the two pixels respectively next adjacent to the pixels having the highest and lowest
35 signal amplitudes (Y1, Y4), and to identify the mean (M) of signal outputs from the eight pixels (Xc) diagonally adjacent to, and arranged around, said four pixels (Yn, Ye, Ys, Yw) in said row and column, to enable an amplitude

comparison to be made according to the result of which one of the said median pair (Y2, Y3) is selected.

15. A signal processing method for estimating luminance for
5 use in a matrix array monochrome image sensor in which
elected luminance-sensing pixels (P) capable of producing
signals representative of luminance are arranged in a
chequerboard pattern with non-luminance-representative
matrix array elements (N) which do not produce signals, the
10 method comprising the steps of: ranking the signal values
(Y1, Y2, Y3, Y4) representative of luminance obtained from
a cluster of four luminance-sensing pixels (Yn, Ye, Ys, Yw)
surrounding a first non-luminance-representative matrix
element (C), analysing the spatial distribution of said
15 ranked signal values so as to detect the presence of any
diagonal luminance contour edge, horizontal luminance
contour stripe or vertical luminance contour stripe at said
first non-luminance-representative matrix element (C), and
determining an estimated discrete signal value
20 representative of luminance for said non-luminance-
representative matrix element (C) based on one or more
middle ranked signal values (Y2, Y3) in a contour-enhancing
fashion dependent upon, firstly, whether any diagonal
luminance contour edge is detected and, secondly, whether
25 any horizontal or vertical luminance contour stripe which
is detected is interpreted as a dark stripe on a light
background or a light stripe on a dark background, wherein
when a horizontal or vertical luminance contour stripe is
detected the signal values representative of luminance
30 obtained from at least second and third luminance-sensing
pixels (X1, X4) disposed respectively within and outwith
the detected luminance contour stripe are compared with the
mean (M) of the signal values obtained from a plurality of
further luminance-sensing pixels (Xc) in the vicinity of
35 said cluster of four luminance-sensing pixels (Yn, Ye, Ys,
Yw) so as to determine whether said horizontal or vertical
stripe is interpreted as a dark stripe on a light
background or a light stripe on a dark background.

16. A signal processing method according to claim 15, wherein said plurality of further luminance-sensing pixels (Xc) comprises eight pixels, each pixel being disposed diagonally adjacent one of said cluster of four luminance-sensing pixels (Yn, Ye, Ys, Yw) surrounding said first non-luminance representative matrix element (C).
17. A signal processing method according to claim 15 or claim 16, wherein said second and third luminance-sensing pixels (X1, X4) are disposed horizontally and vertically opposite said first non-luminance representative matrix element (C) and adjacent to the two of the cluster of four luminance-sensing pixels (Yn, Ye, Ys, Yw) which have the highest and lowest ranked signal values (Y1, Y4).
18. A signal processing method according to any of claims 15 to 17, wherein the steps of the method are repeated for each non-luminance representative matrix element in the matrix array which is at the centre of both a row and a column containing seven matrix elements.
19. A camera (20) comprising a matrix array image sensor (21) and signal processing means (25) formed and arranged for carrying out the signal processing method according to any preceding claim.
20. A camera (20) according to claim 19 when dependent from claim 1 or claim 4, wherein said matrix array image sensor (21) comprises an array of red (R), green (G) and blue (B) pixels, and said elected luminance-sensing pixels are green pixels.
21. A camera (20) according to claim 19 when dependent from claim 1 or claim 4, wherein said matrix array image sensor (21) comprises a mixed colour and monochrome array in which monochrome luminance-sensing pixels (Y) are arranged in a chequerboard pattern with colour-sensing pixels (R, G, B).

22. A camera according to any of claims 19 to 21, wherein
said matrix array image sensor (21) and said signal
5 processing means (25) are provided together in an
integrated circuit.

23. A video camera system incorporating a camera according
to any of claims 19 to 22.

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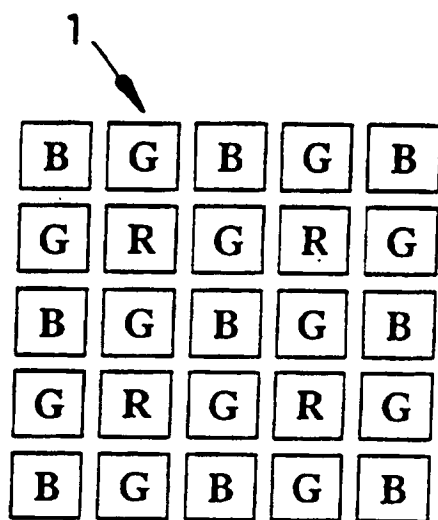
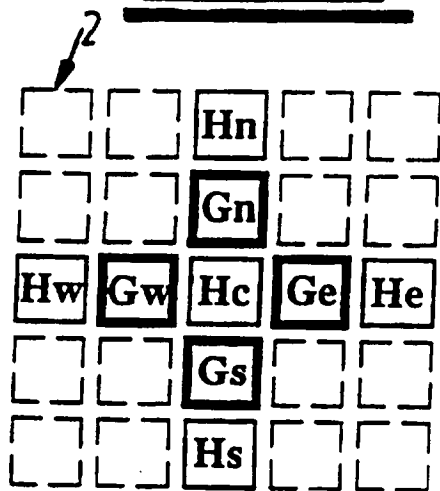
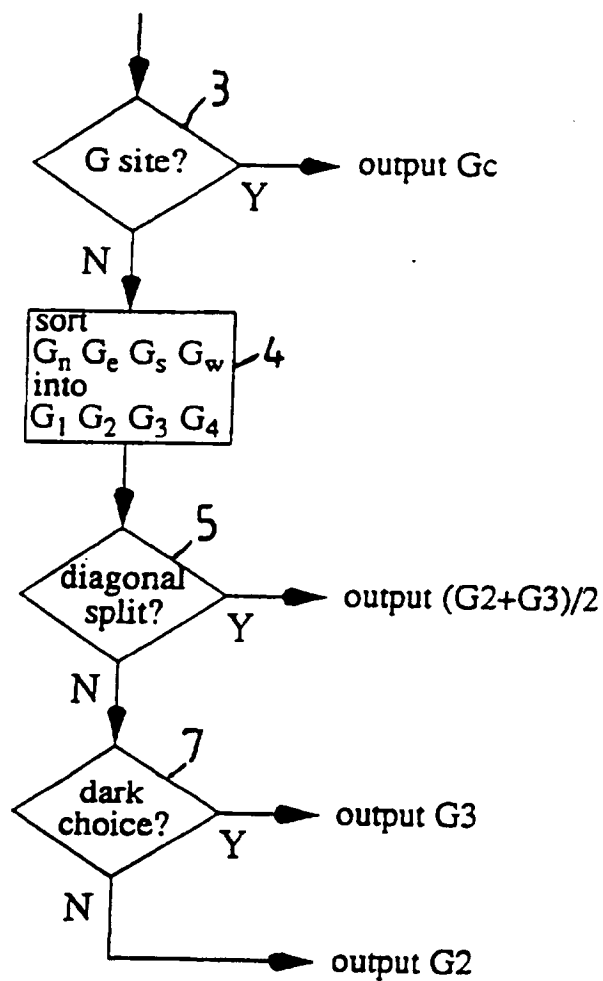
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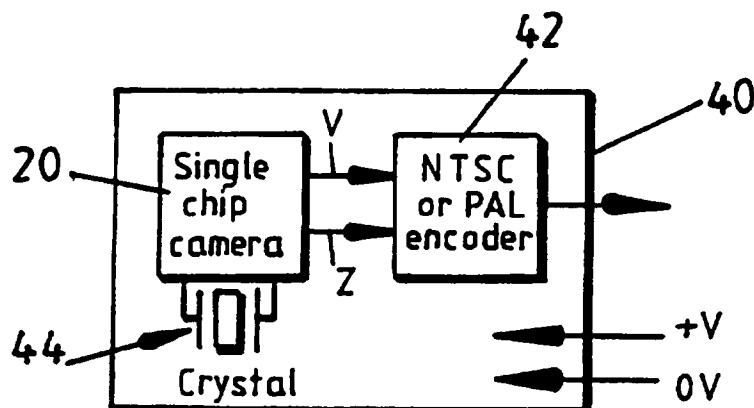
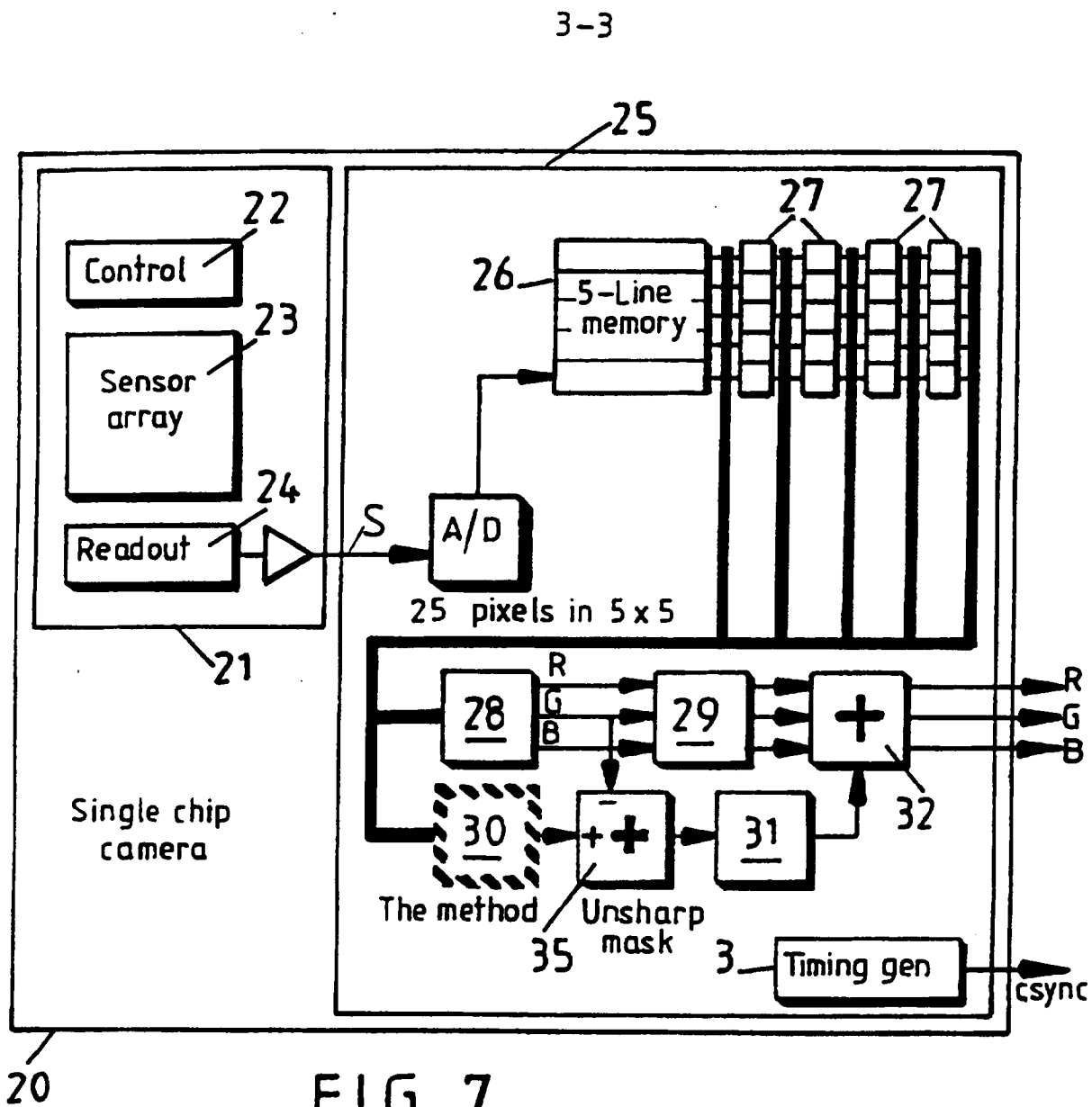
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FIG. 1FIG. 2FIG. 4



A. CLASSIFICATION OF SUBJECT MATTER
IPC 6 H04N9/04

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)
IPC 6 H04N G06T

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practical, search terms used)

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category *	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
A	US 4 630 307 A (COK DAVID R) 16 December 1986 cited in the application see column 1, line 29 - column 3, line 16; figures 2B, 2C, 11-14 see column 4, line 5 - line 44; figure 4 ---	1-23
A	US 5 373 322 A (LAROCHÉ CLAUDE A ET AL) 13 December 1994 see column 1, line 25 - line 64; figures 2, 4 see column 4, line 32 - column 6, line 39 -----	1-23

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Date of the actual completion of the international search

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Patent document cited in search report	Publication date	Patent family member(s)	Publication date
US 4630307 A	16-12-86	EP 0193563 A WO 8601966 A	10-09-86 27-03-86
US 5373322 A	13-12-94	NONE	

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